



Contest Rules

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Disclaimer

The GeekPwn organizer is providing this document solely to help contest teams and players to get familiar with the rules of Robot Agent Challenge. This document is for reference only and subject to the real condition of contest field. The GeekPwn organizer has the right to adjust the content of this document, and reserve the final explanation right of all the Robot Agent Challenge rules.

The latest version of this document will be published on GeekPwn official site. Please always check the latest version. Should there be any difference between the English version and the Chinese version, the Chinese version would prevail.

Change Logs

Version 2.0: Published

Version 2.1: Minor change in Award Criteria section and document layout


Version 2.2: Multiple changes in rules, including added details about multiple robots in group , adjusted rules about surveillance camera and bonus mission, etc.



Notes

When describing size or weight in this document, "m" stands for "meter", "cm" stands for "centimeter", "kg" stands for "kilogram".

Prizes

	1st place: \$15,000-\$30,000 USD	}
	2nd place: \$8,000-\$15,000 USD	
	3rd place: \$3,000-\$8,000 USD.	

The final amount of reward bonus is decided by judges from points ranking, game efficiency, automatic level, creativeness, tech doc submitted etc.

Contest Goal

In this Robot Agent Challenge contest, each team is required to make a robot which can invade a physical mock-up lab room. During the contest, the robot can be remotely controlled by players, or act autonomously, to complete missions and earn corresponding points. Final ranking is based on the total points earned by each team.

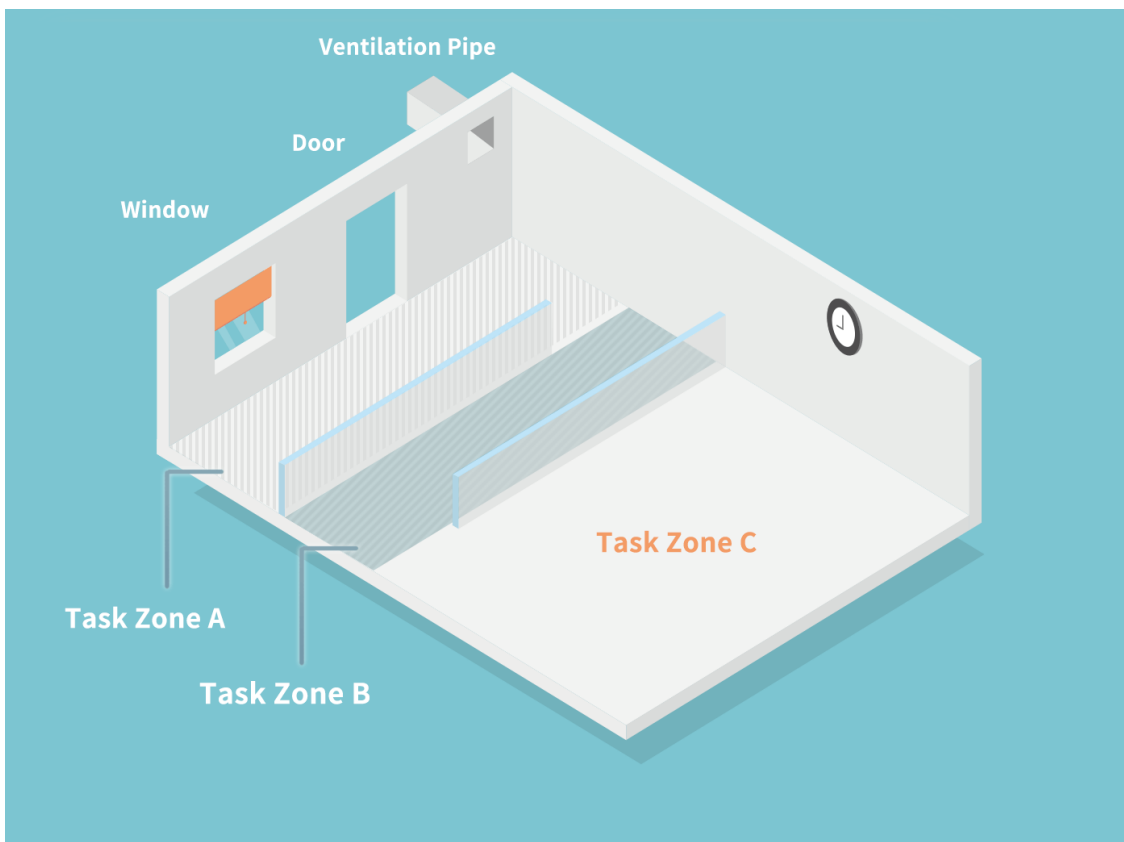
Contest Form

1. Each team will try contest in turn. Each round of contest has max time of 20 minutes. The round of contest is over when time used up to 20 minutes.
2. If contest is interrupted and ended due to robot malfunction, the team can apply for the 2nd chance to restart the round from beginning. In such case, the final points will be computed based on total points earned in the 2nd try minus 10 points as penalty.
3. Each team can learn the detail of contest field in advance before contest. If robot is remotely controlled by player, during the contest, the player can only watch environment via the point view of the controlled robot.
4. Each team can fulfill missions with one single robot, or multiple robots in group. Total weight of all robots in group should be no more than 15kg (including wires used to connect and control robots).
5. Each team can have total team members up to 3.
6. It is forbidden to use destructive manner in contest. If there is any damage of contest facilities caused by player's contest manner, the team will be disqualified.
7. The judges of contest have the final judgement rights on the teams' qualifications and contest results.

☰ Contest Field

The contest field is a physical mock-up lab room with size about 4m(length) * 3m(width) * 2.6m(height). It is divide to 3 mission zones: **Zone A (Entrance)**, **Zone B (Dodging)** and **Zone C (Invasion)**. Robot (or robots in group) should finish Zone A mission before starting Zone B mission, and finish Zone B mission before starting Zone C mission.

The contest field layout is like below:



☰ Contest Missions

/ Mission Zone A: Entrance /

1. Each team should choose only one entrance mission. If there are multiple robots in group, all robots in group should take the same mission. Points corresponding to the mission can be earned only once for each team.
2. Robot (or robots in group) should depart at specified location and have no physical touch with players after started the entrance mission.
3. Please note passing through the door is not allowed.

Missions	Goals	Conditions	Points
Get out of parcel and enter room	Robot should get out of a parcel and reach the specified position in the lab room.	Robot should be in the form of completely concealed parcel , placed on the ground inside the lab door. The parcel is made by player, with size not exceeding 80cm * 80cm * 80cm , total weight with robot(s) no more than 20kg .	10
Enter room through window	Robot should enter through the window and reach the specified position in the lab room.	The size of window is about 1m(height) * 0.6m(width) , height to the ground about 1m , distance to the player about 1.5m .	20



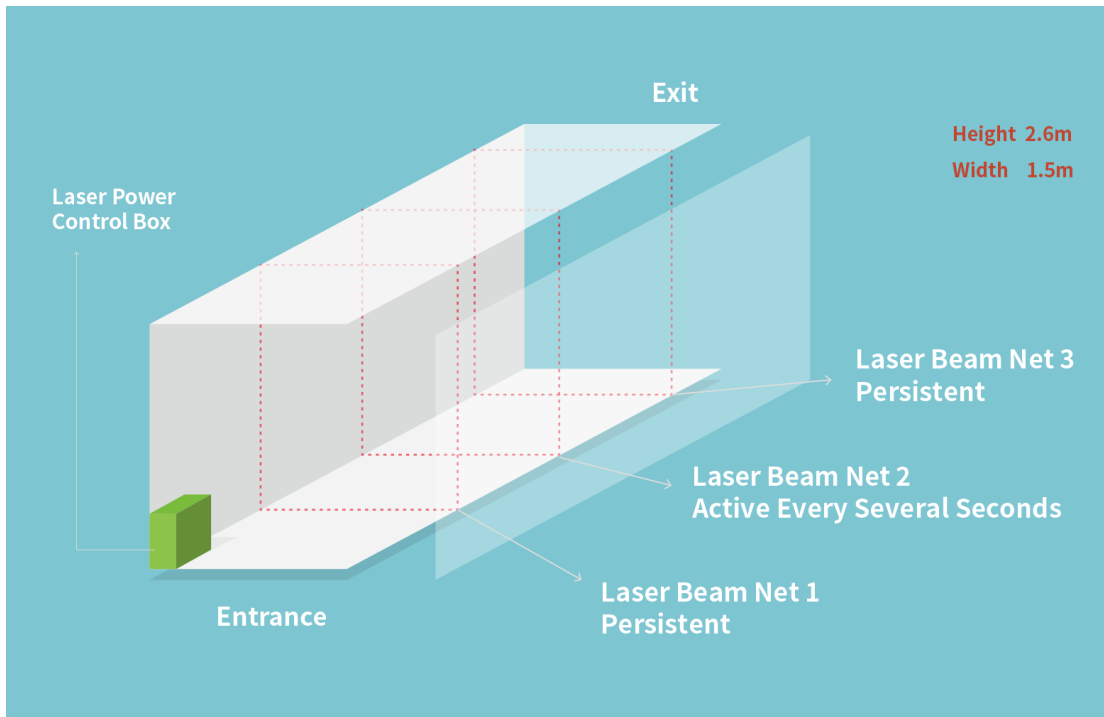
GeekPwn2018 Robot Agent Challenge

<p>Enter room through ventilation pipe</p>	<p>Robot should enter through the ventilation pipe and reach the specified position in the lab room.</p>	<p>The ventilation pipe is near ceiling. It' s square shape with 40cm(height) * 50cm(width) * 1m(length), thickness about 0.5cm, plastic material with smooth surface, vertical entrance and exit without cover.</p>	<p>30</p>
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/ Mission Zone B: Dodging /

1. Each team can choose either dodging laser beams or turning off laser beams as the target mission. If there are multiple robots in group, all robots in group should take the same mission. Points corresponding to each mission can be earned only once for each team.
2. Without triggering any alarm of laser beams, if robot (or robots in group) can turn off laser beams and pass the zone safely, it means the mission completed and the team managed to earn the points.
3. The mission will be aborted if alarm of laser beams is triggered. In such condition, points of previous safely passed laser beams are valid and counted, but the remaining laser beams will contribute no more points. Robot (or robots in group) can still continue the remaining contest, but the remaining contest time will be subtracted 3 minutes as penalty.
4. The space of Zone B is similar to the diagram below: (The laser beam locations, angles, colors etc. are for reference only, not the real effects.)



Missions	Goals	Conditions	Points
Dodge laser beams	Robot should pass laser beam safely without triggering alarm when the laser beam is on.	The space size is about 1.5m (width) * 2.6m(height) . There are 3 bundles of laser beams. Robot will earn 5 points by safely dodging 1 bundle of laser beams.	5*3
Turn off laser beams	Robot should open the door of control box, and press the switch button inside to turn off laser beams.	The control box is on the ground of the space entrance, with size about 30cm(length) * 10cm(width) * 40cm(height) . The box door can be directly opened by pulling its handle lightly. The switch button is on the back side of the control box.	15

/Mission Zone C: Invasion /

1. The first mission “Disturb surveillance camera” in the list is special. It should be completed as the first mission of Zone C, otherwise this mission can be ignored.
2. For other missions except the first mission “Disturb surveillance camera” below, robot can take one or multiple different missions in any order. If there are multiple robots in groups, these robots can take different missions simultaneously.
3. Points of each mission completed will be summed up.

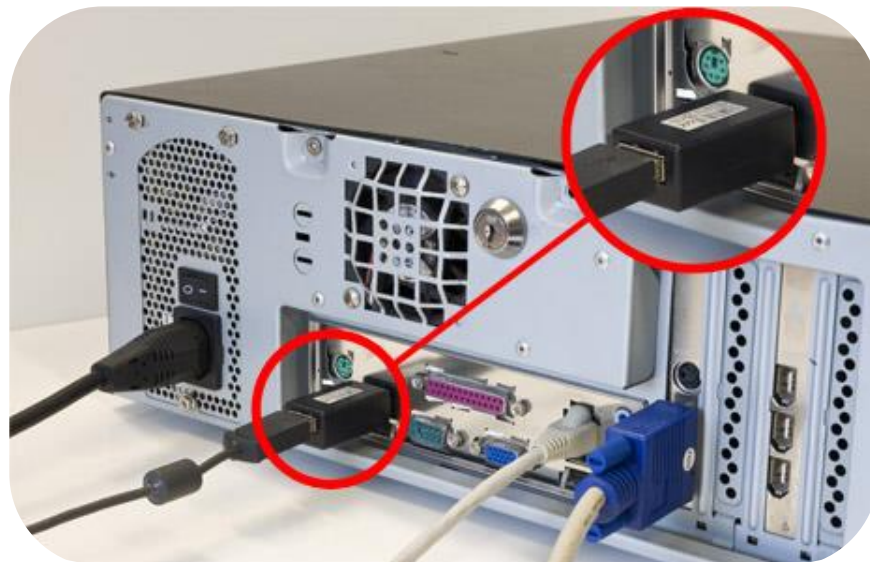
Missions	Goals	Conditions	Points
Disturb surveillance camera	Robot should disturb surveillance camera so that the camera could not monitor in efficient way.	The height of camera is about 2m . Its stand can be turned around by force. The disturbed status should sustain to the end of invasion.	50
Place a covert listening device	Robot should place a covert listening device at the specified place under a chair bottom.	The height from the ground to the back of chair bottom is about 40cm . The dummy covert listening device is provided by player, size not exceeding 0.5cm * 5cm * 5cm	20
Open safe to get secret information on card	Robot should input password of safe to open it, and get secret information from a card inside.	The safe is on the ground. The size of password panel is about 5cm * 5cm . With correct password typed, the door of safe can be opened directly by pulling its handle lightly. The card is A5 size with secret information on top of it, laid on the bottom of the safe. (Check the safe example picture below) .	40

<p>Open a book to get secret information on card</p>	<p>Robot should get the secret information on top of a card which is placed between pages of a book.</p>	<p>The book is about A5 size, thickness about 1cm, laid on desktop with height about 75cm, the book spine align with the edge of desktop. The card is A5 size with secret information on top of it, laid between pages of the book.</p>	<p>50</p>
<p>Plug a malicious USB device to computer</p>	<p>Robot should plug a malicious USB device to computer and press the power button to turn it on.</p>	<p>The computer is on the ground. The USB port (height 19cm – 22cm) and power button (height 31cm – 33cm) is on the front panel of computer. The USB device will be provided by organizer.</p>	<p>60</p>
<p>Plug a keyboard recorder</p>	<p>Robot should pull out the keyboard from computer USB port, and plug a keyboard recorder between keyboard and USB port on the back panel of computer.</p>	<p>The computer is on the ground. The USB port (height 25cm – 30cm) is on the back panel of computer. The keyboard recorder will be provided by organizer. (Check the keyboard recorder example picture below)</p>	<p>120</p>

■ Safe example:



■ Keyboard recorder example:



/ Bonus Mission /

Missions	Goals	Conditions	Points
Retreat	Robot (or all robots in group) should retreat back to outside of room in reasonable and safe way.	Robot (or all robots in group) can retreat back to parcel and restore the parcel to its original status, or get out of lab room via window or ventilation pipe. Retreating through door is not allowed. Robot can take this bonus mission only after finished at least 1 mission of Zone C.	10

 Award Criteria

1. Criteria: Team should complete at least one Zone C mission to enter the award candidate queue.
2. Ranking: Team ranking is based on total points of each team. If there is a tie, the ranking will be determined by:
 - a) Control manner: Robot acting autonomously will be in higher ranking position than remotely being controlled by player.
 - b) Mission difficulty: Ranking according to the highest points of the each completed Zone C mission. Higher points higher ranking.
 - c) Mission time: Ranking according to the total time consumed when robot completed its last Zone C mission. Less total time higher ranking.



Contact Us

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